

MAJ : 12/05/2012



*Non contractual picture*

**$\mu$ AME 17 actuator has an astatic design, it generates bidirectional forces with a very high resolution.**

## 1 - Description

- Its patented design is cost effective and robust.
- The system is driven by a stepper motor. It permits a stable and constant force application without power supply thanks to its irreversible mechanics.
- The output rod with its floating head allows angular and radial misalignments without generating any parasitic torque not friction.
- The actuator can be customized upon customer request

## 2 – Possible applications

- Mirror deformation for wavefront correction
- Application of forces with high resolution
- Static actuator with controlled force

### 3 - Spécifications techniques

#### Motor :

Stepper motor

Supply voltage	24V
Starting current	0.5 A

#### Specifications :

Force resolution	0.5 mN/step
Force range	$\pm 17$ N
Linearity (after calibration)	0,1%
Hysteresis	1%
Repeatability	0.01 N RMS
Accuracy (after calibration)	0.02 N RMS

#### Duty ratio :

According to application, Please ask.

#### Speed :

Up to 4N/s

#### Working temperature :

20 to 22 °C

#### Actuator mass :

About 100 g

#### Options :

- Low outgassing version
- Dedicated connector
- Controller
- Interface for fixation to a mirror

