

NANOPOSITIONING LINEAR STAGES NLS II x series

DATASHEET ISP09R025FPI0022 G ISP SYSTEM® PATENTED

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Image is for illustrative purposes only

1 - On-the-fly scanning – Nano-positioning

- Sub-nanometer positioning resolution
- Absolute position closed-loop control
- Travel range of up to 10 mm
- Excellent closed-loop speed control on the whole stroke (speed variation <10%)
- X-Y movement through combination of two stages
- Patented guiding system for optimized straightness in 3 directions
- Dedicated electronics hardware and software available
- Triggered for synchronisation with customer application
- Vacuum and Ultra High Vacuum versions available
- Free aperture through the stage
- Remote motor \rightarrow no electromagnetic perturbation near the sample to be studied

The **NLS + series** is a product range based on a reliable technology providing nanometric resolution motion in horizontal direction. These stages were created to address the new needs in nanotechnology (e.g. Scanning Electron Microscope, laser lithography, atomic force microscopy, wafers manufacturing, spectroscopy ...).

They are particularly adapted to on-the-fly scanning applications.

The x-y motion is obtained through a combination of two NLS stages

2 - Main characteristics

TECHNOLOGY	AVAILABILITIES
Motor	remote Voice-coil (VC)
Pressure compliance	Atmospheric (ATM), Low Vacuum (LV), High Vacuum (HV) or Ultra High Vacuum (UHV)
Motion controller	Closed Loop (CL)
Displacement sensors	Optical (O) or Capacitive (C)
Travel	Up to 10 mm
Static resolution	0.2nm at 2Hz
Sensor dynamic resolution	10nm dynamic resolution at 1KHz
Static accuracy	+/-10nm
Near straightness in the three directions	1µrad/ ±30 nm (10 mm travel)
(angular/linear)	
Pay load	250 g
Scanning mode	On-the-fly scan
Maximum speed	10 mm/s
Speed variation over 10mm stroke	<10% of nominal speed
Working direction	Horizontally
Temperatures	Working temperature 0 to 30°C; Baking 150°C
Size	156x120x43.5mm
Weight	1.3kg
Pody motoriala	

*Please notice that further data and measurements are available on request.





3 - NLS II x series Motion controller architecture



NLS controllers are Windows®-based interfaces providing powerful diagnostic, development, and analysis tools (simple automation tasks, observe the system behavior, system optimization...) on a user-friendly platform. Jog-mode allows the user to program motion profiles and to call them manually or in operating.

This document belongs to ISP SYSTEM, it cannot be used, copied or communicated without a prior written agreement. The mentioned information, herein, are subject to change. Thanks to consult ISP SYSTEM NLS controller has a host-mode operation allowing you to send commands with your PC via Ethernet for immediate execution. Jog-mode is completed by fly-scan and step-by-step modes available to triggered motion and acquisition on the same clock. Synchronous data transfer can be initialized by the user and acquisitions can be triggered on a master input clock.

Motion profiles are designed and developed to optimize actuator displacement and obtain the best behavior.

NLS MOTION CONTROLLER		
Platform	NLS software	
Languages supported	C, C++, LabVIEW (VIs supplied),	
Operating system	Windows 7	
Operating profiles	Manual, jog, flyscan and step-by-step	
Data acquisition	Synchronous	
Acquisition triggered	Yes	

	SPECIFICATIONS
Power supply	100-240VAC/50-60Hz 4.5A
Resolution	24-bit
Motion profiles	Position and speed
Speed profile	Trapezoidal
Communication	Ethernet
Motor supply	±12VDC/1A
Position sensor	Sin/Cos
Homing sensor	Photomicrosensor (accuracy ±1µm)
Trigger input	0-5V TTL (max freq. 1kHz)
Working temperature	0 to 50°C
Storage temperature	-20°C to+70°C
Cooling	Forced convection
Dimensions	4U depth 260mm
Weight	8 Kg
Maximum cable length between stage and controller	2m (P _{atm}), 3m (vacuum) If longer cables necessary, to be discussed acc. to the application

Please notice that further data and measurements are available on request.

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